Transport noise Measurement uncertainty



GOOD PRACTICE GUIDE

May 2012

Uncertainty in noise measurements

All measurement results have an inherent uncertainty or inaccuracy about their true value. In the case of noise measurements, the source and propagation path are examples of areas of uncertainty. Knowledge of uncertainty factors will assist with the interpretation of the measurement results, indicate differences which may not be significant and identify areas where greater detail can improve assessments. Section 5.4.3 of NZS 6806 recommends the use of uncertainty budgets, and this good practice guide describes typical sources of uncertainty in road-traffic noise measurement and how to calculate a budget. An example is shown overleaf. These procedures are based on the guide book by Craven and Kerry, as referenced by NZS 6806.

Sources and level of uncertainty

The potential sources of uncertainty in a measurement of road-traffic noise include the following:

- Variations in the traffic flow and number of heavy goods vehicles compared to the values assumed for these parameters. For example, if the road typically carries 22,000 vehicles per day, what is the level of traffic during the measurement period?
- Weather conditions, especially the wind as it will influence the noise level at the measurement point depending on direction and speed.
- The position of the measurement point in relation to the source.
 What is the accuracy of the source to receiver distance measurement?

Identifying all the sources and magnitudes of the uncertainties provides a means of quantifying the total uncertainty of a measurement (the 'uncertainty budget') and also a method to minimise some of them, thus improving the accuracy of the final result.

Assessing the level of uncertainty in a measurement results in two quantities:

- The 'confidence interval' or 'uncertainty' the margin within which the true value can be said to lie (eg ± 3 dB)
- The 'level of confidence' the number expressing the degree of confidence in the uncertainty result (eg 95%)

Thus a measured noise level of $L_{\text{Aeq}(24\text{h})}$ 57 dB with these levels of uncertainty would be quoted as:

 $L_{Aeq(24h)}$ 57 dB ± 3 dB with a confidence level of 95%

For ease of reading, it is not necessary to repeat this full notation every time a noise level is stated in a road-traffic noise assessment report.

Uncertainty budget

To obtain the level of uncertainty, the procedure below is carried out.

List all sources of measurement uncertainty

(source, propagation path, receiver)



Determine the magnitude of each uncertainty

Either: calculate from repeated measurements, or estimate based on experience, or use a figure from literature.



Convert uncertainty into decibels



Calculate the standard uncertainty for each source of uncertainty u_p u_y u_y . . .

The standard uncertainty for a normal distribution is:

$$u = \frac{S}{\sqrt{n}}$$

where s is the estimated standard deviation of a set of n samples.

The standard uncertainty for a rectangular distribution is:

$$u = \frac{x}{\sqrt{3}}$$

for $\pm x$ uncertainty.



Calculate the combined uncertainty u_c

$$u_c = \sqrt{u_1^2 + u_2^2 + u_3^2 + \cdots}$$



Calculate the expanded uncertainty U

$$U = ku_c$$

(coverage factor k = 2 for 95% confidence limits)

Example

This is an example of an uncertainty budget for a road-traffic noise measurement, carried out as part of the assessment of an altered road in accordance with NZS 6806. Measurements of the existing road-traffic noise were made at the façade of a building. The potential sources of uncertainty have been identified and categorised under source, transmission path and receiver.

The magnitude of the traffic flow Calculations of the A rectangular The standard uncertainty uncertainty is the variation from the Annual traffic noise level have distribution of for a rectangular Average Daily Traffic (AADT). In this case it distribution is: $u = \frac{1}{2}$ been made with uncertainty means that is estimated it could vary by ± 1000 $22.000 \pm 1000 \text{ vpd}$. the real value can fall [For a normal distribution vehicles per day (vpd). This uncertainty can This results in a noise anywhere between the the standard uncertainty be reduced by making measurements of level uncertainty of uncertainty magnitude is: $u = \frac{s}{\sqrt{\eta}}$] traffic flow during the noise survey. ± 0.2 dB. with equal probability. Source of Magnitude of **Conversion of Distribution** Standard NZTA research report 446 uncertainty uncertainty to dB uncertainty dB uncertainty provides guidance on variation due to weather. Source 0.2 dB Traffic flow 1000 in 22,000 vpd Rectangular 0.11 dB % HGV and 5% at 90km/hr 3.1 dB 1.79 dB Rectangular to 15% at 110km/hr Mean speed There should be no change **Transmission path** in ground and topography during a survey. The report 3.0 dB Weather 3.0 dB Rectangular 1.73 dB should describe these Ground No change conditions at the time of the measurements. No change Topography Receiver Position 2m in 100m. 0.1 dB 0.05 dB Rectangular This relates to the accuracy 1.9 dB 1.9 dB 1.10 dB of the source to receiver Instrumentation Rectangular distance measurement, Background < 0.1 dB and uncertainty in Façade reflection 1.0 dB 1.0 dB 0.58 dB Rectangular repositioning the

The uncertainty of a Class 1 sound level meter under practical measurement conditions.

microphone for any repeat

measurements.

The road-traffic noise dominated the measurement.

The uncertainty in the reflected noise from the façade, which depends on the construction. The standard façade correction is 2.5 dB, and the uncertainty is estimated as \pm 1.0 dB.

The result of this uncertainty assessment is that the measured noise level has an uncertainty of \pm 5.6 dB with a confidence level of 95%

2.78 dB

5.57 dB

Further information on uncertainty can be obtained in:

N.J. Craven and G. Kerry. A good practice guide on the sources and magnitude of uncertainty arising in the practical measurement of environmental noise. University of Salford. 2001.

Combined uncertainty $(u_c = \sqrt{u_1^2 + u_2^2 + u_3^2 + \cdots})$

Expanded uncertainty ($U = ku_c$, k=2 for 95% confidence)

V.K. Dravitzki, R.J. Jackett and C.W.B. Wood. The variability of road traffic noise and implications for compliance with the noise conditions of roading designations. NZTA research report 446. 2011

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